

Real-valued  $4 \times 3 \times 3$  arrays have rank 5 with positive probability

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## Introduction

We consider a real-valued  $4 \times 3 \times 3$  array of which the elements are drawn from a 36-dimensional continuous distribution  $P$ . We assume that  $P(A) = 0$  if and only if  $L(A) = 0$ , where  $L$  denotes the Lebesgue measure and  $A$  is an arbitrary Borel set in  $\mathbb{R}^{36}$ . The three  $4 \times 3$  slices of the array are denoted by  $\mathbf{X}$ ,  $\mathbf{Y}$  and  $\mathbf{Z}$ . We know that, with probability 1, the three-way rank of the array is either 5 or 6; see Ten Berge and Stegeman (2004, Table 2). Here, we will show that rank 5 occurs with positive probability. It is not yet known whether rank 6 occurs with positive probability or not.

Our result is obtained by showing that all arrays randomly sampled from a small 36-dimensional environment of a particular  $4 \times 3 \times 3$  array, have a full rank-5 decomposition. Let  $\mathbf{X}$ ,  $\mathbf{Y}$  and  $\mathbf{Z}$  be randomly sampled as explained above. Ten Berge and Kiers (1999) have shown that, with probability 1, there exist nonsingular matrices  $\mathbf{S}$  and  $\mathbf{T}$  such that

$$\mathbf{SXT} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}, \quad \mathbf{SYT} = \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \quad \mathbf{SZT} = \begin{bmatrix} f_1 & g_1 & h_1 \\ f_2 & g_2 & h_2 \\ f_3 & g_3 & h_3 \\ f_4 & g_4 & h_4 \end{bmatrix}, \quad (1)$$

where the last slice can be treated as randomly sampled from a 12-dimensional continuous distribution. Hence, without loss of generality we may assume that the array is of the form as in (1), i.e.

$$\mathbf{X} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}, \quad \mathbf{Y} = \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \quad \mathbf{Z} = \begin{bmatrix} f_1 & g_1 & h_1 \\ f_2 & g_2 & h_2 \\ f_3 & g_3 & h_3 \\ f_4 & g_4 & h_4 \end{bmatrix}. \quad (2)$$

Moreover, since all arrays randomly sampled from a small 36-dimensional environment of  $(\mathbf{X}, \mathbf{Y}, \mathbf{Z})$  can be transformed to the form (1), we only need to show that a full rank-5 decomposition exists for  $\mathbf{X}$  and  $\mathbf{Y}$  as in (2) and a small 12-dimensional environment of a particular  $\mathbf{Z}$ . For this, we will take

$$\mathbf{Z} = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 2 & 3 \\ 1 & 3 & 5 \\ 1 & 4 & 7 \end{bmatrix}. \quad (3)$$

### Construction of a rank-5 decomposition

We start with the array in (2) and show how a rank-5 decomposition can be obtained. This is done by adding a fifth row to the slices in (2) and using the approach of Ten Berge (2004) to find a rank-5 decomposition of a  $5 \times 3 \times 3$  array. We denote our  $5 \times 3 \times 3$  array by

$$\tilde{\mathbf{X}} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \\ x_1 & x_2 & x_3 \end{bmatrix}, \quad \tilde{\mathbf{Y}} = \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ y_1 & y_2 & y_3 \end{bmatrix}, \quad \tilde{\mathbf{Z}} = \begin{bmatrix} f_1 & g_1 & h_1 \\ f_2 & g_2 & h_2 \\ f_3 & g_3 & h_3 \\ f_4 & g_4 & h_4 \\ z_1 & z_2 & z_3 \end{bmatrix}, \quad (4)$$

where we may choose the values of  $\mathbf{x} = (x_1, x_2, x_3)'$ ,  $\mathbf{y} = (y_1, y_2, y_3)'$  and  $\mathbf{z} = (z_1, z_2, z_3)'$ . Let  $\mathbf{f} = (f_1, f_2, f_3, f_4)'$ ,  $\mathbf{g} = (g_1, g_2, g_3, g_4)'$  and  $\mathbf{h} = (h_1, h_2, h_3, h_4)'$ . It can be seen that we may set  $x_1 = x_2 = x_3 = y_3 = 0$  without loss of generality. Indeed, subtracting from the fifth row in each slice  $x_1$  times the first row,  $x_2$  times the second row,  $x_3$  times the third row and  $y_3$  times the fourth row yields an array with the same rank as (4). Somewhat abusing the notation, the remaining elements on the fifth row will be denoted as  $\mathbf{y} = (y_1, y_2)'$  and  $\mathbf{z} = (z_1, z_2, z_3)'$ . Hence, we consider the following array:

$$\tilde{\mathbf{X}} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \quad \tilde{\mathbf{Y}} = \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ y_1 & y_2 & 0 \end{bmatrix}, \quad \tilde{\mathbf{Z}} = \begin{bmatrix} f_1 & g_1 & h_1 \\ f_2 & g_2 & h_2 \\ f_3 & g_3 & h_3 \\ f_4 & g_4 & h_4 \\ z_1 & z_2 & z_3 \end{bmatrix}. \quad (5)$$

The following rank-5 decomposition of (5) will be derived:

$$\tilde{\mathbf{X}} = \mathbf{A} \mathbf{I}_5 \mathbf{B}', \quad \tilde{\mathbf{Y}} = \mathbf{A} \mathbf{C} \mathbf{B}', \quad \tilde{\mathbf{Z}} = \mathbf{A} \mathbf{D} \mathbf{B}', \quad (6)$$

with  $\mathbf{A}$  (5×5),  $\mathbf{B}$  (3×5) and  $\mathbf{C}$  and  $\mathbf{D}$  diagonal matrices. If the fifth row of  $\mathbf{A}$  is deleted, a rank-5 decomposition of the 4×3×3 array in (2) is the result.

Next, we show how to derive the component matrices  $\mathbf{A}$ ,  $\mathbf{B}$ ,  $\mathbf{C}$  and  $\mathbf{D}$ . We assume that  $\mathbf{A}$  is nonsingular. It can be seen that  $\mathbf{C}\mathbf{A}^{-1}\tilde{\mathbf{X}} - \mathbf{A}^{-1}\tilde{\mathbf{Y}} = \mathbf{A}^{-1}\tilde{\mathbf{Z}} - \mathbf{D}\mathbf{A}^{-1}\tilde{\mathbf{X}} = \mathbf{0}$ . Hence, the  $j$ -th row  $\mathbf{a}'_j$  of  $\mathbf{A}^{-1}$  should satisfy  $\mathbf{a}'_j(c_j\tilde{\mathbf{X}} - \tilde{\mathbf{Y}}) = \mathbf{a}'_j(\tilde{\mathbf{Z}} - d_j\tilde{\mathbf{X}}) = \mathbf{0}'$ , where  $c_j$  and  $d_j$  are the diagonal elements of  $\mathbf{C}$  and  $\mathbf{D}$ , respectively. Set the first element of  $\mathbf{a}_j$  to 1. From (5) it follows that  $\mathbf{a}'_j(c_j\tilde{\mathbf{X}} - \tilde{\mathbf{Y}}) = \mathbf{0}'$  is equivalent to

$$\mathbf{a}_j = \begin{pmatrix} 1 \\ c_j - \beta_j y_1 \\ c_j^2 - \beta_j y_1 c_j - \beta_j y_2 \\ c_j^3 - \beta_j y_1 c_j^2 - \beta_j y_2 c_j \\ \beta_j \end{pmatrix}, \quad (7)$$

for some scalar  $\beta_j$ . It remains to satisfy  $\mathbf{a}'_j(\tilde{\mathbf{Z}} - d_j\tilde{\mathbf{X}}) = \mathbf{0}'$ , i.e.  $\mathbf{a}_j$  has to be orthogonal to the three columns of  $\tilde{\mathbf{Z}} - d_j\tilde{\mathbf{X}}$ . For  $\mathbf{a}_j$  in (7), this is equivalent to the vector  $\begin{pmatrix} 1 \\ \beta_j \end{pmatrix}$  being orthogonal to the columns of the 2×3 matrix

$$\mathbf{W}_j = \begin{bmatrix} F^{(1)}(c_j, d_j) & G^{(1)}(c_j, d_j) & H^{(1)}(c_j, d_j) \\ F^{(2)}(c_j) & G^{(2)}(c_j, d_j) & H^{(2)}(c_j, d_j) \end{bmatrix}, \quad (8)$$

where the expressions for the elements of  $\mathbf{W}_j$  are given in the Appendix. For the vector  $\begin{pmatrix} 1 \\ \beta_j \end{pmatrix}$  to be orthogonal to the columns of  $\mathbf{W}_j$ , we must have  $\text{rank}(\mathbf{W}_j) = 1$ . We ensure this by choosing  $c_j$  and  $d_j$  such that

$$\det \begin{bmatrix} F^{(1)}(c_j, d_j) & G^{(1)}(c_j, d_j) \\ F^{(2)}(c_j) & G^{(2)}(c_j, d_j) \end{bmatrix} = \det \begin{bmatrix} F^{(1)}(c_j, d_j) & H^{(1)}(c_j, d_j) \\ F^{(2)}(c_j) & H^{(2)}(c_j, d_j) \end{bmatrix} = 0, \quad (9)$$

but not  $F^{(1)}(c_j, d_j) = F^{(2)}(c_j) = 0$ . The first determinant in (9) equals

$$e_3 c_j^3 + (e_{21} + e_{22} d_j) c_j^2 + (e_{11} + e_{12} d_j) c_j + (e_{01} + e_{02} d_j + e_{03} d_j^2), \quad (10)$$

where the coefficients  $e_k$  depend on  $\mathbf{f}$ ,  $\mathbf{g}$ ,  $\mathbf{h}$ ,  $\mathbf{y}$  and  $\mathbf{z}$ . The expressions for  $e_k$  are given in the Appendix. The second determinant in (9) equals

$$\tilde{e}_3 c_j^3 + (\tilde{e}_{21} + \tilde{e}_{22} d_j) c_j^2 + (\tilde{e}_{11} + \tilde{e}_{12} d_j + \tilde{e}_{13} d_j^2) c_j + (\tilde{e}_{01} + \tilde{e}_{02} d_j + \tilde{e}_{03} d_j^2), \quad (11)$$

where the coefficients  $\tilde{e}_k$  depend on  $\mathbf{f}, \mathbf{g}, \mathbf{h}, \mathbf{y}$  and  $\mathbf{z}$ . The expressions for  $\tilde{e}_k$  are given in the Appendix. The following lemma specifies the solutions  $(c_j, d_j)$  for which

$$F^{(1)}(c_j, d_j) = F^{(2)}(c_j) = 0.$$

Lemma 1: The expression  $F^{(1)}(c_j, d_j) = F^{(2)}(c_j) = 0$  is equivalent to:

$$-(f_4 y_1) c_j^2 - (f_3 y_1 + f_4 y_2) c_j + (z_1 - f_3 y_2 - f_2 y_1) = 0, \quad (12)$$

$$d_j = f_4 c_j^3 + f_3 c_j^2 + f_2 c_j + f_1. \quad (13)$$

*Proof.* It can be seen (see Appendix) that (12) is equivalent to  $F^{(2)}(c_j) = 0$  and (13) is equivalent to  $F^{(1)}(c_j, d_j) = 0$ . This completes the proof.  $\square$

Next, we determine  $(c_j, d_j)$  which satisfy both (10) and (11). We set  $y_1 = 0$ . Then  $e_{03} = \tilde{e}_{13} = 0$  (see Appendix) and  $d_j$  can be determined from (10) as

$$d_j = - \left( \frac{e_3 c_j^3 + e_{21} c_j^2 + e_{11} c_j + e_{01}}{e_{22} c_j^2 + e_{12} c_j + e_{02}} \right). \quad (12)$$

Substituting (12) into (11) yields that  $c_j$  can be found as a root of a 7-th degree polynomial. We denote this polynomial by

$$Q(c) = q_7 c^7 + q_6 c^6 + q_5 c^5 + q_4 c^4 + q_3 c^3 + q_2 c^2 + q_1 c + q_0. \quad (13)$$

The coefficients  $q_k$  depend only on  $\mathbf{f}, \mathbf{g}, \mathbf{h}, \mathbf{y}$  and  $\mathbf{z}$ . Their expressions are given in the Appendix. Since we need five solutions for  $c_j$ , the polynomial  $Q$  must have at least five real roots. Because  $y_1 = 0$ , there is only one solution  $(c_j, d_j)$  for which  $F^{(1)}(c_j, d_j) = F^{(2)}(c_j) = 0$  (see Lemma 1). The  $c_j$  of this flawed solution is also a root of  $Q$ . Therefore,  $Q$  must have seven real roots. One root is discarded and five out of the six remaining roots are used as  $c_j$ . This is again the partial uniqueness result obtained by Ten Berge (2004). Once the  $c_j$  and  $d_j$  are known, the scalars  $\beta_j$  can be chosen as

$-F^{(1)}(c_j, d_j)/F^{(2)}(c_j)$ . Then  $\mathbf{A}^{-1}$  follows from (7) and  $\mathbf{B}$  can be determined from  $\mathbf{B}' = \mathbf{A}^{-1}\tilde{\mathbf{X}}$ .

Hence, for given vectors  $\mathbf{f}$ ,  $\mathbf{g}$ ,  $\mathbf{h}$ , the problem is to choose  $\mathbf{y}$  and  $\mathbf{z}$  (under the restriction  $y_1 = 0$ ) such that the polynomial  $Q$  in (13) has seven real roots.

### Rank 5 occurs with positive probability

We have applied the procedure above to the  $4 \times 3 \times 3$  array in (2) with  $\mathbf{Z}$  as in (3). For

$$\mathbf{y} = \begin{pmatrix} 0 \\ -0.42 \end{pmatrix}, \quad \mathbf{z} = \begin{pmatrix} -0.06 \\ -0.15 \\ -0.27 \end{pmatrix}, \quad (14)$$

the polynomial  $Q$  has the following seven real roots: -9.85, -1.46, -0.86, -0.69, -0.68, 0.31 and 3.46. From Lemma 1 it follows that the flawed solution for  $c_j$  is given by

$$c_j = \frac{z_1 - f_3 y_2}{f_4 y_2} = -0.86. \quad (15)$$

Hence, six real roots of  $Q$  remain and a rank-5 decomposition can be constructed as above.

Next, we show that a full rank-5 decomposition is also possible in a small environment of  $\mathbf{Z}$ , where  $\mathbf{y}$  and  $\mathbf{z}$  remain the same. Define

$$S_8 = \{(q_0, q_1, \mathbf{K}, q_7) : Q \text{ has seven real roots}\}. \quad (16)$$

Since  $Q$  has a unique set of seven roots (for  $q_7 \neq 0$ ), we may write

$$Q(c) = \alpha(\lambda_1 - c)(\lambda_2 - c)(\lambda_3 - c)(\lambda_4 - c)(\lambda_5 - c)(\lambda_6 - c)(\lambda_7 - c), \quad (17)$$

where  $\alpha$  is a scaling parameter and  $\lambda_i$  are the roots of  $Q$ . By equating (13) and (17), it can be verified that there exists a continuous mapping from  $(\alpha, \lambda_1, \lambda_2, \mathbf{K}, \lambda_7)$  to  $(q_0, q_1, \mathbf{K}, q_7)$ . Moreover, since  $Q$  has a unique set of seven roots (for  $q_7 \neq 0$ ), this mapping is one-to-one up to a permutation of  $(\lambda_1, \lambda_2, \mathbf{K}, \lambda_7)$ . This implies that the set  $S_8$  has positive 8-dimensional volume. The boundary points of  $S_8$  are those  $(q_0, q_1, \mathbf{K}, q_7)$  for which  $Q$  has at least two identical real roots. Then an arbitrary close approximation by a polynomial with one pair of complex roots is possible, where the imaginary parts of

the complex roots are close to zero. Hence,  $S_8$  is a closed set. If  $Q$  has seven distinct real roots for  $(q_0, q_1, K, q_7)$ , then  $(q_0, q_1, K, q_7)$  is an interior point of the set  $S_8$ , and within a small environment of  $(q_0, q_1, K, q_7)$  the polynomial  $Q$  also has seven real roots. Since the coefficients  $(q_0, q_1, K, q_7)$  are continuous functions of  $\mathbf{f}$ ,  $\mathbf{g}$  and  $\mathbf{h}$ , it follows that in a small environment of  $\mathbf{Z}$  in (3), with  $\mathbf{y}$  and  $\mathbf{z}$  as in (14), the polynomial  $Q$  will still have seven real roots. Therefore, a full rank-5 decomposition is possible in a small environment of  $\mathbf{Z}$ . This shows that for real-valued  $4 \times 3 \times 3$  arrays of which the elements are randomly sampled from a continuous distribution, rank 5 occurs with positive probability.

## References

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## Appendix

The expressions for the elements of the matrix  $\mathbf{W}_j$  in (8) are as follows:

$$\begin{aligned} F^{(1)}(c, d) &= f_4 c^3 + f_3 c^2 + f_2 c + (f_1 - d), \\ G^{(1)}(c, d) &= g_4 c^3 + g_3 c^2 + (g_2 - d)c + g_1, \\ H^{(1)}(c, d) &= h_4 c^3 + (h_3 - d)c^2 + h_2 c + h_1, \\ F^{(2)}(c) &= -(f_4 y_1)c^2 - (f_3 y_1 + f_4 y_2)c + (z_1 - f_3 y_2 - f_2 y_1), \\ G^{(2)}(c, d) &= -(g_4 y_1)c^2 - (g_3 y_1 + g_4 y_2)c + [z_2 - g_3 y_2 - (g_2 - d)y_1], \end{aligned}$$

$$H^{(2)}(c, d) = -(h_4 y_1) c^2 - [(h_3 - d) y_1 + h_4 y_2] c + [z_3 - (h_3 - d) y_2 - h_2 y_1].$$

The expressions for the coefficients  $e_k$  in (10) are as follows:

$$\begin{aligned} e_3 &= (f_4 z_2 - g_4 z_1), \\ e_{21} &= (f_3 z_2 - g_3 z_1) - (f_1 g_4 - g_1 f_4) y_1 - (f_2 g_4 - g_2 f_4) y_2, \\ e_{22} &= g_4 y_1 - f_4 y_2, \\ e_{11} &= (f_2 z_2 - g_2 z_1) + (f_3 g_2 - g_3 f_2) y_2 - (f_1 g_3 - g_1 f_3) y_1 - (f_1 g_4 - g_1 f_4) y_2, \\ e_{01} &= (f_1 z_2 - g_1 z_1) + (f_2 g_1 - g_2 f_1) y_1 + (f_3 g_1 - g_3 f_1) y_2, \\ e_{02} &= (f_1 + g_2) y_1 + g_3 y_2 - z_2, \\ e_{03} &= -y_1. \end{aligned}$$

The expressions for the coefficients  $\tilde{e}_k$  in (11) are as follows:

$$\begin{aligned} \tilde{e}_3 &= (f_4 z_3 - h_4 z_1), \\ \tilde{e}_{21} &= (f_3 z_3 - h_3 z_1) - (f_1 h_4 - h_1 f_4) y_1 - (f_2 h_4 - h_2 f_4) y_2, \\ \tilde{e}_{22} &= z_1 + h_4 y_1, \\ \tilde{e}_{11} &= (f_2 z_3 - h_2 z_1) + (f_3 h_2 - h_3 f_2) y_2 - (f_1 h_3 - h_1 f_3) y_1 - (f_1 h_4 - h_1 f_4) y_2, \\ \tilde{e}_{12} &= (f_1 + h_3) y_1 + (f_2 + h_4) y_2, \\ \tilde{e}_{13} &= -y_1, \\ \tilde{e}_{01} &= (f_1 z_3 - h_1 z_1) + (f_2 h_1 - h_2 f_1) y_1 + (f_3 h_1 - h_3 f_1) y_2, \\ \tilde{e}_{02} &= h_2 y_1 + (f_1 + h_3) y_2 - z_3, \\ \tilde{e}_{03} &= -y_2. \end{aligned}$$

The expressions for the coefficients  $q_k$  in (13) are as follows:

$$q_7 = \tilde{e}_3 e_{22}^2 - \tilde{e}_{22} e_3 e_{22},$$

$$q_6 = 2\tilde{e}_3 e_{22} e_{12} + \tilde{e}_{21} e_{22}^2 - \tilde{e}_{22} (e_3 e_{12} + e_{21} e_{22}) - \tilde{e}_{12} e_3 e_{22} + \tilde{e}_{03} e_3^2,$$

$$q_5 = \tilde{e}_3 (2e_{22} e_{02} + e_{12}^2) + 2\tilde{e}_{21} e_{22} e_{12} - \tilde{e}_{22} (e_3 e_{02} + e_{21} e_{12} + e_{11} e_{22}) + \tilde{e}_{11} e_{22}^2 - \tilde{e}_{12} (e_3 e_{12} + e_{21} e_{22}) - \tilde{e}_{02} e_3 e_{22} + 2\tilde{e}_{03} e_{21} e_3,$$

$$q_4 = 2\tilde{e}_3 e_{12} e_{02} + \tilde{e}_{21} (2e_{22} e_{02} + e_{12}^2) - \tilde{e}_{22} (e_{21} e_{02} + e_{11} e_{12} + e_{01} e_{22}) + 2\tilde{e}_{11} e_{22} e_{12} - \tilde{e}_{12} (e_3 e_{02} + e_{21} e_{12} + e_{11} e_{22}) + \tilde{e}_{01} e_{22}^2 - \tilde{e}_{02} (e_3 e_{12} + e_{21} e_{22}) + \tilde{e}_{03} (e_{21}^2 + 2e_{11} e_3),$$

$$q_3 = \tilde{e}_3 e_{02}^2 + 2\tilde{e}_{21} e_{12} e_{02} - \tilde{e}_{22} (e_{11} e_{02} + e_{01} e_{12}) + \tilde{e}_{11} (2e_{22} e_{02} + e_{12}^2) - \tilde{e}_{12} (e_{21} e_{02} + e_{11} e_{12} + e_{01} e_{22}) + 2\tilde{e}_{01} e_{22} e_{12} - \tilde{e}_{02} (e_3 e_{02} + e_{21} e_{12} + e_{11} e_{22}) + 2\tilde{e}_{03} (e_{01} e_3 + 2e_{11} e_{21}),$$

$$q_2 = \tilde{e}_{21} e_{02}^2 - \tilde{e}_{22} e_{01} e_{02} + 2\tilde{e}_{11} e_{12} e_{02} - \tilde{e}_{12} (e_{11} e_{02} + e_{01} e_{12}) + \tilde{e}_{01} (2e_{22} e_{02} + e_{12}^2) - \tilde{e}_{02} (e_{21} e_{02} + e_{11} e_{12} + e_{01} e_{22}) + \tilde{e}_{03} (2e_{01} e_{21} + e_{11}^2),$$

$$q_1 = \tilde{e}_{11} e_{02}^2 - \tilde{e}_{12} e_{01} e_{02} + 2\tilde{e}_{01} e_{12} e_{02} - \tilde{e}_{02} (e_{11} e_{02} + e_{01} e_{12}) + 2\tilde{e}_{03} e_{01} e_{11},$$

$$q_0 = \tilde{e}_{01} e_{02}^2 - \tilde{e}_{02} e_{01} e_{02} + \tilde{e}_{03} e_{01}^2.$$